Beyond Value Iteration for Parity Games: Strategy Iteration with Universal Trees

Zhuan Khye Koh Georg Loho







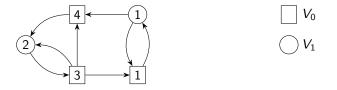
Occupies Complexity of deciding the winner

3 Winning certificate from a universal tree

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Strategy iteration

Setting: A directed graph G = (V, E) with partition $V = V_0 \sqcup V_1$, and a priority function $\pi : V \to \{1, 2, ..., d\}$.



• Nodes in V_0 and V_1 are owned by players Even and Odd respectively.

• A token is placed on a starting node $v \in V$. In every turn, the owner of the current node moves the token to an out-neighbour. \implies an infinite walk *P* (assume *G* is sinkless).

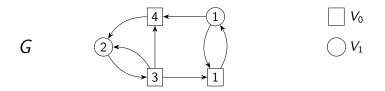
• If the highest priority occuring infinitely often in P is even, then Even wins. Otherwise, Odd wins.

Positional Determinacy: Starting from any node $v \in V$, either Even or Odd can guarantee to win using a positional strategy.

• A (positional) strategy for Even is a function $\sigma : V_0 \to V$ such that $v\sigma(v) \in E$ for all $v \in V_0$. Its strategy subgraph is $G_{\sigma} = (V, E_{\sigma})$ where

$$E_{\sigma} = \{v\sigma(v) : v \in V_0\} \cup \{vw \in E : v \in V_1\}.$$

A strategy τ for Odd and its strategy subgraph G_{τ} are defined similarly.



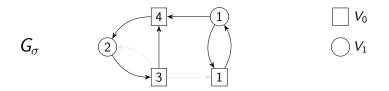
Problem: Given (G, π) and starting node $v \in V$, output the winner.

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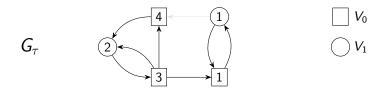
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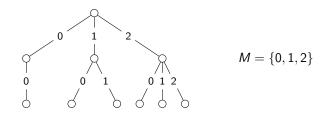
Complexity of deciding the winner

- Belongs to $NP \cap coNP$.
- Important in logic and verification, e.g., polynomial-time equivalent to the model-checking problem for modal μ -calculus.
- Pre-2017 algorithms were exponential or subexponential time.
- Quasi-polynomial time [Calude, Jain, Khoussainov, Li, Stephan '17].

• Many other quasi-polynomial algorithms soon follow: [Fearnley, Jain, Keijzer, Schewe, Stephan, Wojtczak '17] [Gimbert, Ibsen–Jensen '17] [Jurdziński, Lazić '17] [Lehtinen '18] [Parys '19] [Lehtinen, Schewe, Wojtczak '19] [Daviaud, Jurdziński, Thejaswini '20] [Benerecetti, Dell'Erba, Mogavero, Schewe, Wojtczak '21].

• Most of them have been unified via the notion of a <u>universal tree</u> [Czerwiński, Daviaud, Fijalkow, Jurdziński, Lazić, Parys '19].

Ordered tree

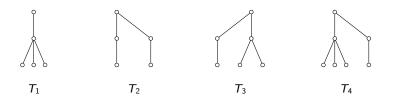


Def: Given a totally ordered set (M, \leq) , an ordered tree T is a prefix-closed set of tuples whose elements are drawn from M.

- Elements in *M* induce branching directions at every vertex $v \in V(T)$.
- The tuple corresponding to a vertex v is given by the root-v path.
- \leq extends lexicographically to V(T).
- L(T) := leaf set of T. Assume every leaf has the same depth.

Universal tree

• Given ordered trees T and T', T embeds into T' ($T \sqsubseteq T'$) if there exists an injective function $f : V(T) \rightarrow V(T')$ such that

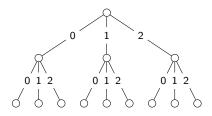


Def: An (ℓ, h) -universal tree is an ordered tree T' such that $T \sqsubseteq T'$ for all ordered trees T of height at most h and with at most ℓ leaves.

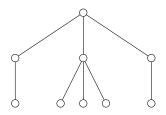
Thm: Every universal tree has at least quasi-polynomially many leaves. [Czerwiński et al. '19].

Examples of universal trees

- Perfect (ℓ , h)-universal tree:
 - Every leaf is an *h*-tuple of integers from $\{0, 1, \ldots, \ell 1\}$.
 - Contains l^h leaves.
- Succinct (ℓ, h) -universal tree [Jurdziński, Lazić '17]:
 - ► Every leaf is an *h*-tuple of binary strings with at most [log *l*] bits in total.
 - Contains $\ell^{\log h + O(1)}$ leaves.



A perfect (3,2)-universal tree.



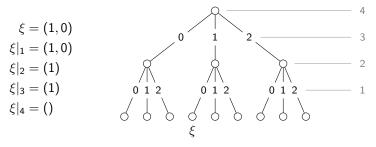
A succinct (3,2)-universal tree.

Winning certificate from a universal tree

- Let $\overline{L}(T) := L(T) \cup \{\top\}$, where $\top > v$ for all $v \in V(T)$.
- Given an instance (G, π) with n = |V|, a node labeling is a function $\mu: V \to \overline{L}(T)$ for some (n, d/2)-universal tree T.
- For a leaf $\xi \in L(T)$, we index its tuple by $(\xi_{d-1}, \xi_{d-3}, \dots, \xi_1)$.

Intuition: records how many times an odd priority is encountered.

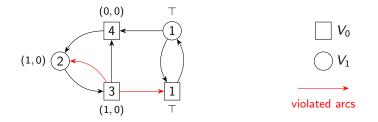
• For a priority p, the *p*-truncation of ξ is obtained by deleting the components with index less than p.



Winning certificate from a universal tree

Def: A node labeling μ is feasible in *G* if Even has a strategy σ such that every arc *vw* in G_{σ} satisfies

- If $\pi(v)$ is even, then $\mu(v)|_{\pi(v)} \ge \mu(w)|_{\pi(v)}$.
- ▶ If $\pi(v)$ is odd, then $\mu(v)|_{\pi(v)} > \mu(w)|_{\pi(v)}$ or $\mu(v) = \mu(w) = \top$.

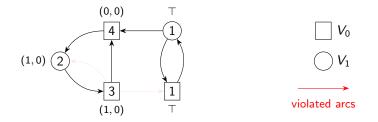


Thm: Let μ^* be a node labeling which is feasible in *G* and has minimal \top -support. Even wins from $v \in V \iff \mu^*(v) \neq \top$ [Jurdziński '00].

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Value iteration

Def: Given $\mu : V \to \overline{L}(T)$ and $vw \in E$, let $lift(\mu, vw)$ be the smallest element $\xi \in \overline{L}(T)$ such that $\xi \ge \mu(v)$ and vw is non-violated after setting $\mu(v)$ to ξ .

Value-Iteration(G, π, T)
μ(v) ← min L(T) for all v ∈ V
while μ is not feasible: μ(v) ← min_{vw∈δ⁺(v)} lift(μ, vw) for some node v ∈ V₀ whose outgoing arcs δ⁺(v) are all violated or μ(v) ← lift(μ, vw) for some violated arc vw ∈ E where v ∈ V₁
return μ

- Returns the least fixed point of G in $\Theta(n|L(T)|)$ iterations.
- Also called the progress measure algorithm [Jurdziński '00].

Behaviour of value iteration

• Not robust against its worst-case runtime:

$$(G,\pi)$$

• If d is even, then the two additional nodes see every element in $\overline{L}(T)$. $\implies \Omega(|L(T)|)$ time.

Idea: Iterate over strategies instead of arcs:

- Fix a strategy τ for Odd.
- Update μ to the least fixed point of G_{τ} .
- Pivot to a "better" strategy τ' for Odd, and repeat.

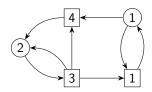
Impossibility result: The label set $\overline{L}(T)$ is not fit for strategy iteration [Ohlmann '22].

Strategy-Iteration (G, π, T, τ)

- 1 $\mu(v) \leftarrow \min L(T)$ for all $v \in V$
- **2** $\mu \leftarrow$ least fixed point of G_{τ} which is at least μ
- **3 while** μ is not feasible in *G*:

Odd pivots to a strategy τ' by selecting violated arc(s) $\tau \leftarrow \tau'$

 $\mu \leftarrow$ least fixed point of \textit{G}_{τ} which is at least μ



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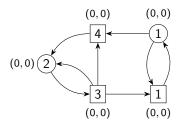
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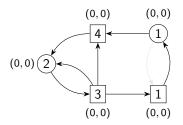
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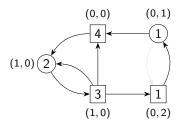
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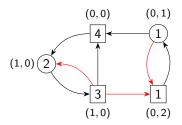
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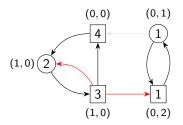
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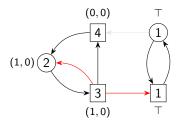
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Computing the least fixed point of G_{τ}

• Value iteration on the 1-player game G_{τ} still takes $\Theta(|L(T)|)$ time.

Idea: Approach the least fixed point from above.

 Inspired by label-correcting (e.g. Bellman–Ford) and label-setting (e.g. Dijkstra) techniques from shortest path.

• We give an efficient method to compute the least fixed point of G_{τ} for any universal tree T.

Running times for specific T

- $O(d(m + n \log n))$ for a perfect (n, d/2)-universal tree.
- $O(mn^2 \log n \log d)$ for a succinct (n, d/2)-universal tree.
- O(mn² log³ n log d) for a Strahler (n, d/2)-universal tree (introduced by [Daviaud, Jurdziński, Thejaswini '20]).



• We now have a strategy iteration framework for parity games that works with universal trees.

• Total running time is upper bounded by value iteration's running time.

Open question: Is there a subquasi-polynomial pivot rule using some universal tree?